



# Boundary layer high order concentration statistics

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(Luhar et al., 2000)

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- ✓ parametrizing the dispersion around the centre of the cloud.

# Lagrangian model for the barycenter

$$dx_m = U(z_m)dt$$

$$dw_m = a_m(t, w_m, z_m)dt + b_m(t, z_m)dW(t)$$

$$dz_m = w_m dt$$

$$\frac{\partial P_m}{\partial t} + w \frac{\partial P_m}{\partial z_m} = - \frac{\partial [a(t, w_m, z_m)P_m]}{\partial w_m} + \frac{\sigma_m^2}{T_m} \frac{\partial^2 P_m}{\partial w_m^2}$$

Langevin  
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Fokker-Planck

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$$a(w_m, z_m, t) = \alpha_m(z_m, t)w_m^2 + \beta_m(z_m, t)w_m + \gamma_m(z_m, t)$$

(Franzese, 2003)

Langevin  
equation

Fokker-Planck

Diffusion  
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Quadratic  
assumption

# Lagrangian model for the barycenter

$$\frac{\partial}{\partial t} \langle w^m \rangle + \alpha_z \langle w^{m+1} \rangle + \beta_z \langle w^m \rangle + \gamma_z \langle w^{m-1} \rangle = \frac{1}{m} \frac{\partial \langle w^{m+1} \rangle}{\partial z} - 2(m-1) \frac{\sigma_m^2}{T_m} \langle w^{m-2} \rangle$$

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Centroid Vertical Acceleration Parameters:

$$\alpha(z_m) = \frac{(1/3)(\partial \langle w_m^3 \rangle / \partial t + \langle w_m^4 \rangle / \partial z_m)}{\langle w_m^4 \rangle - \langle w_m^3 \rangle^2 / \langle w_m^2 \rangle - \langle w_m^2 \rangle^2}$$
$$- \frac{\langle w_m^3 \rangle / (2 \langle w_m^2 \rangle) [\partial \langle w_m^3 \rangle / \partial z_m - 2 \langle w_m^2 \rangle / T_m] + \langle w_m^2 \rangle \partial \langle w_m^2 \rangle / \partial z_m}{\langle w_m^4 \rangle - \langle w_m^3 \rangle^2 / \langle w_m^2 \rangle - \langle w_m^2 \rangle^2}$$

$$\beta_m(z_m) = \frac{1}{2 \langle w_m^2 \rangle} \left[ \frac{\partial \langle w_m^2 \rangle}{\partial t} + \frac{\partial \langle w_m^3 \rangle}{\partial z_m} - 2 \langle w_m^3 \rangle \alpha_m(z_m) \right] - \frac{1}{T_m}$$

$$\gamma_m(z_m) = \frac{\partial \langle w_m^2 \rangle}{\partial z_m} - \langle w^2 \rangle \alpha_m(z_m)$$

# Energy Filter and Partition of Energy

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Filter Function

$$\langle w_m^n \rangle = \langle w^n \rangle \left[ 1 - \left( \frac{d^2}{d^2 + z_i^2} \right)^{\frac{1}{3}} \right]^{n/2}$$

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$$t_s = [\sigma_0^2 / (g \varepsilon)]^{1/3}$$

# Relative Concentration PDF

$$\langle c^n(x, z) \rangle = \int \langle c_r^n \rangle p_m(x, z_m) dz_m$$

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$$p_{cr}(c|x, z, z_m) = \frac{\lambda^\lambda}{\langle c_r \rangle \Gamma(\lambda)} \left( \frac{c}{\langle c_r \rangle} \right)^{\lambda-1} e^{-\frac{\lambda c}{\langle c_r \rangle}}$$

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 $\lambda = 1/i_{cr}^2$

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# Relative vertical position PDF

## Gaussian Parametrisation

$$p_{zr}(x, z, z_m) = \frac{1}{\sqrt{2\pi}\sigma_{zr}} \sum_{n=-N}^N \left[ e^{-\frac{(z-z_m+2nz_i)^2}{2\sigma_{zr}^2}} + e^{-\frac{(-z-z_m+2nz_i)^2}{2\sigma_{zr}^2}} \right]$$

Franzese (2003)

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## Skewed Parametrisation

$$p_{zr}(x, z, z_m) = \sum_{j=1}^2 \sum_{n=-N}^N \frac{a_j}{\sqrt{2\pi}\sigma_j} \left[ e^{-\frac{(z-z_m+2nz_i-\bar{z}_j)^2}{2\sigma_j^2}} + e^{-\frac{(-z-z_m+2nz_i-\bar{z}_j)^2}{2\sigma_j^2}} \right]$$

Luhar et al. (2000)

Dosio and De Arellano (2006)

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$$S_{zr} = \frac{\langle (z - \langle z \rangle)^3 \rangle - \langle (z_m - \langle z_m \rangle)^3 \rangle}{\sigma_{zr}^3}$$

# Case studies:

## CBL

Water tank dispersion experiments:  
Willis and Deardorff (1976, 1978,  
1981).

The turbulence used as input of the  
Lagrangian stochastic model is described  
in Franzese et al. (1999) and Franzese  
(2003).

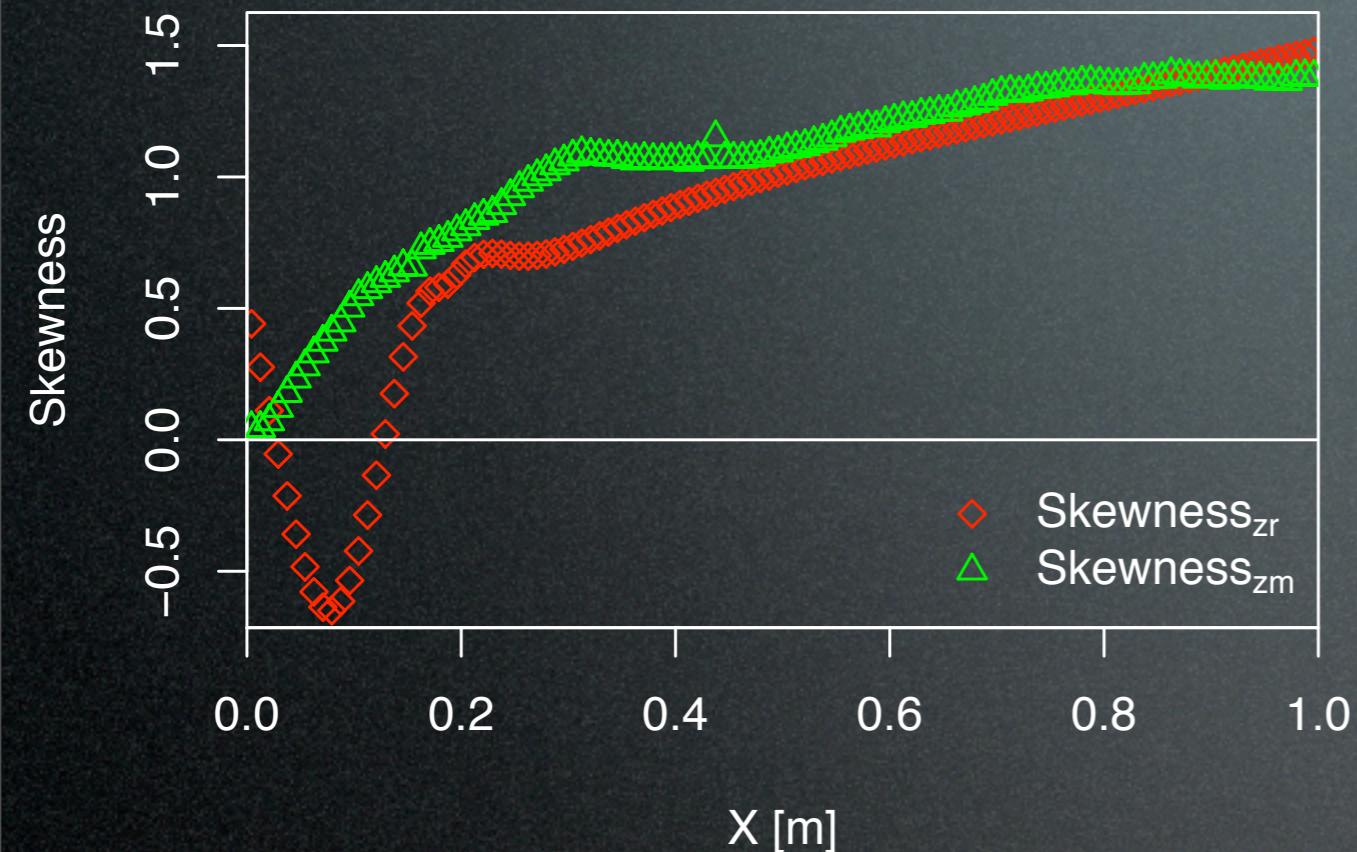
## Canopy

Simulated vegetal canopy from wind  
tunnel experiments: Raupach et al.  
(1986), Legg et al. (1986), Coppin et al.  
(1986).

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Lagrangian stochastic model was  
derived by polynomial and spline fit of  
the experimental data of Raupach et al.  
(1986), Legg et al. (1986), Cassiani et  
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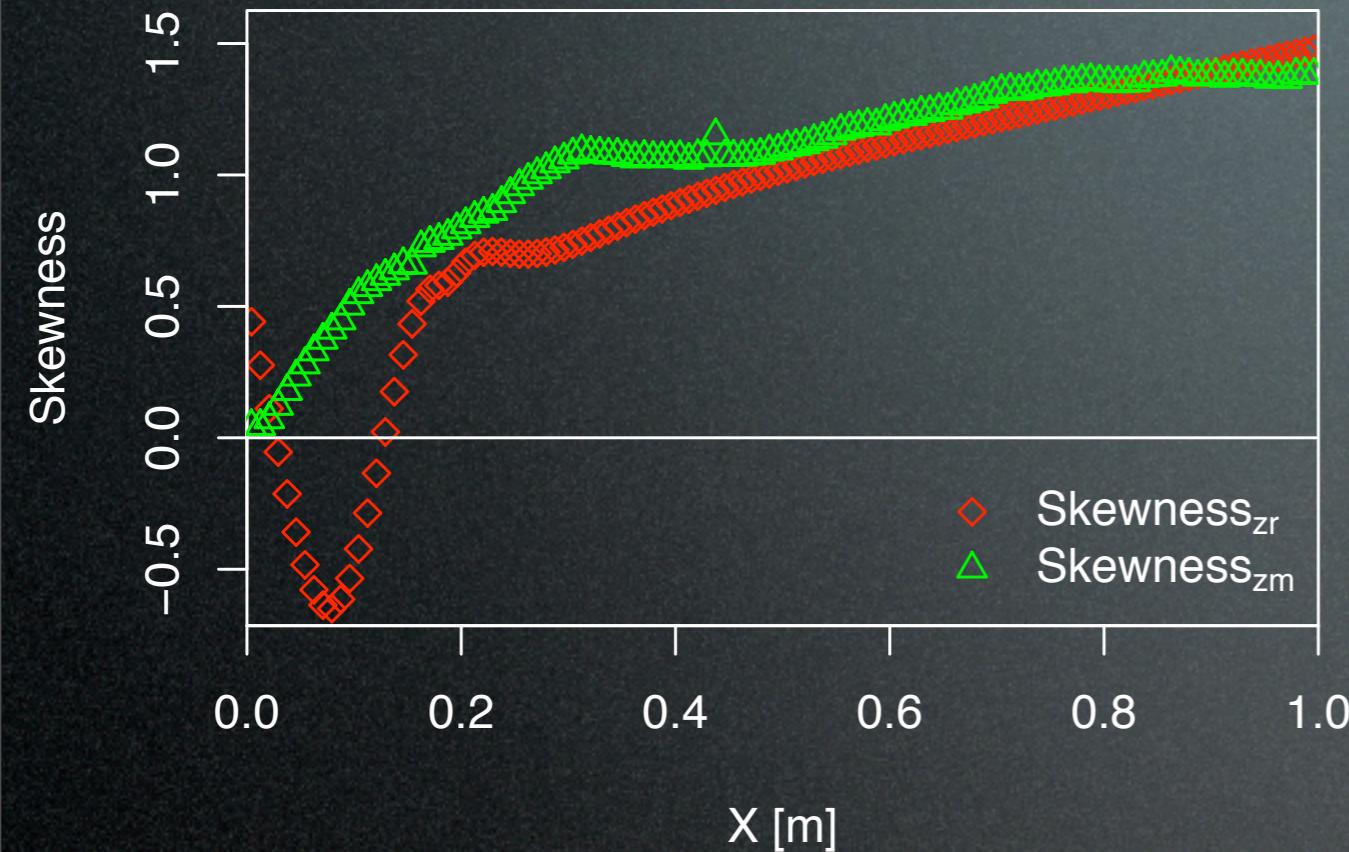
# Skewness of the single particle vertical position relative to the barycenter

Canopy

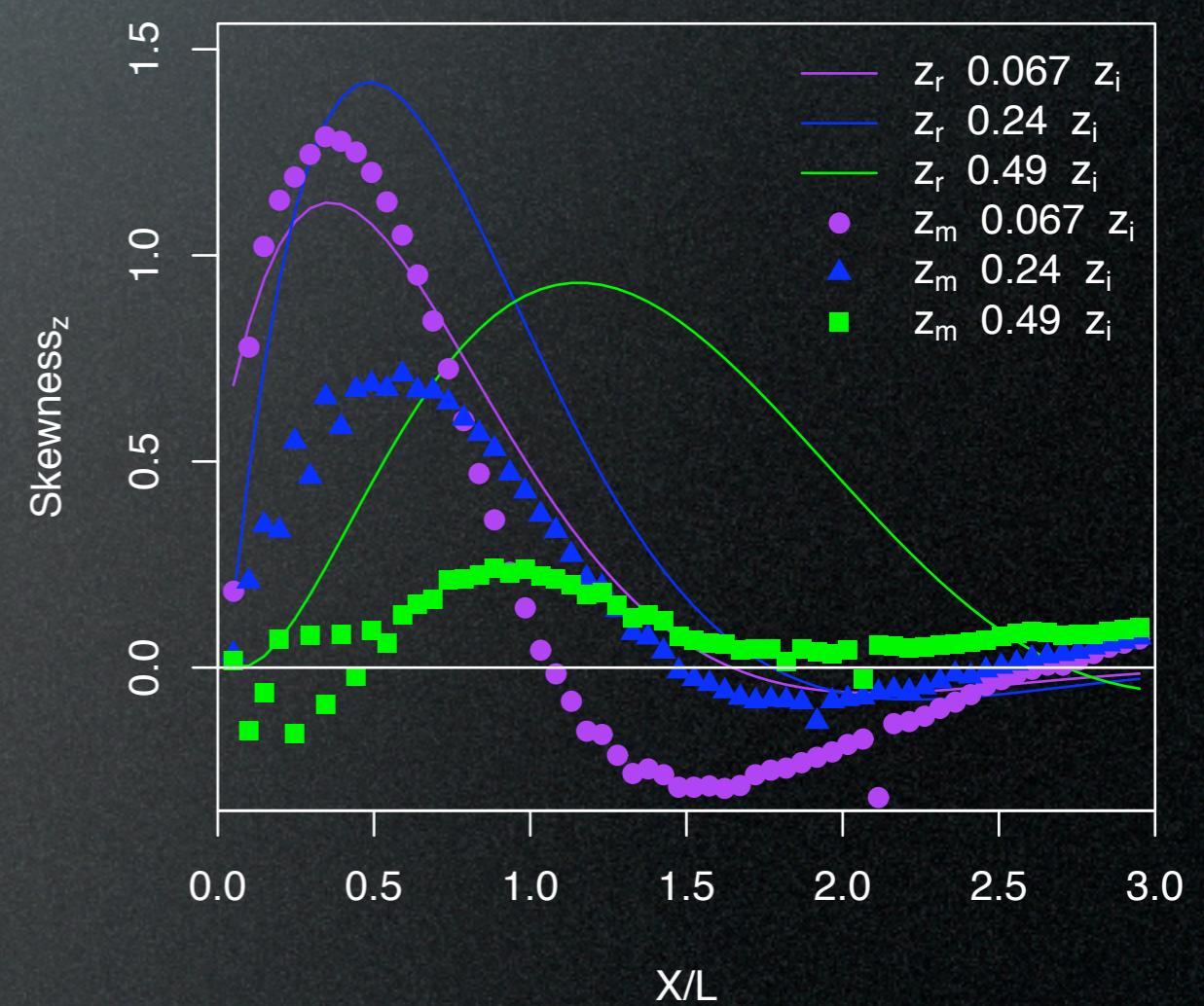


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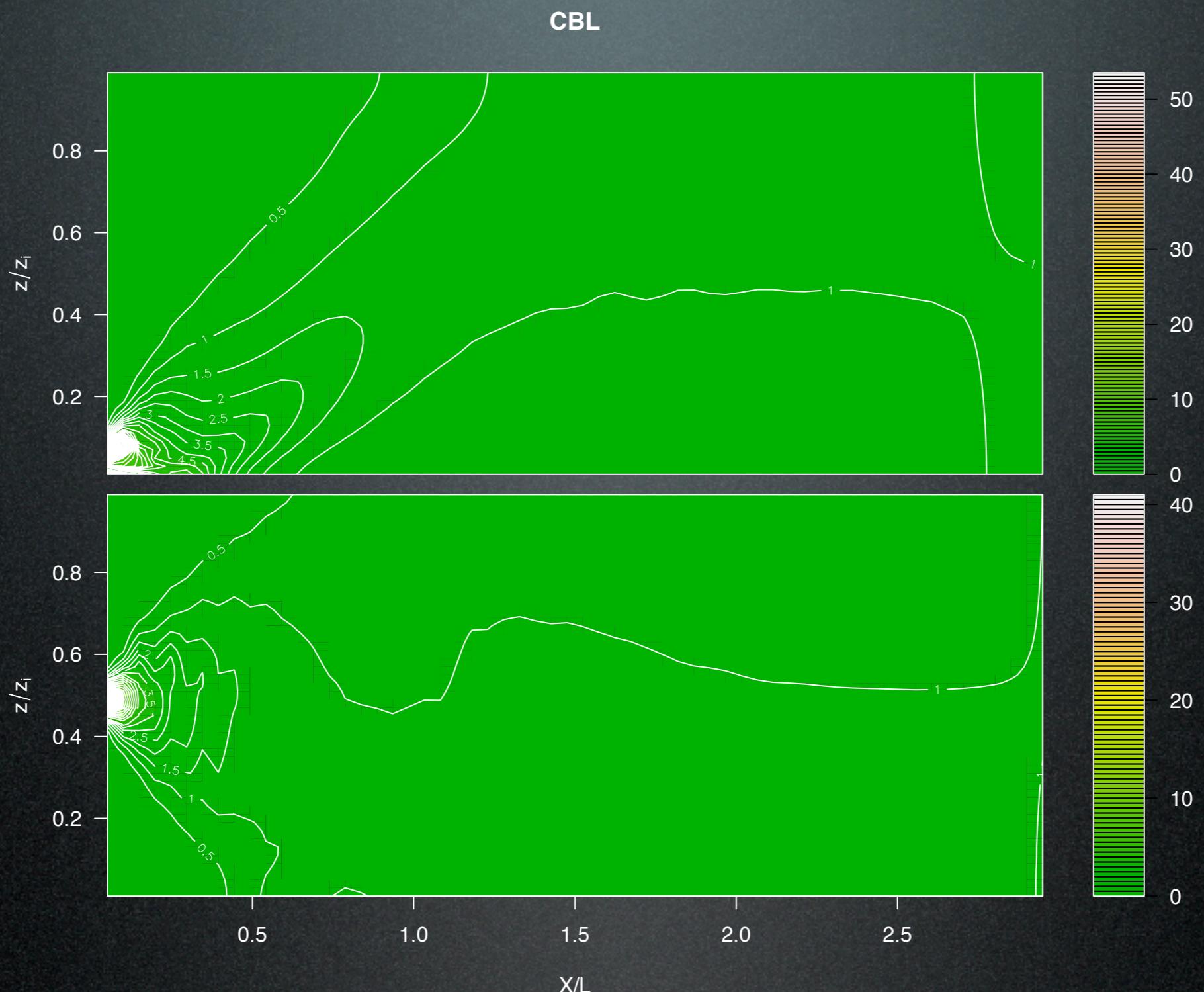
Canopy



CBL

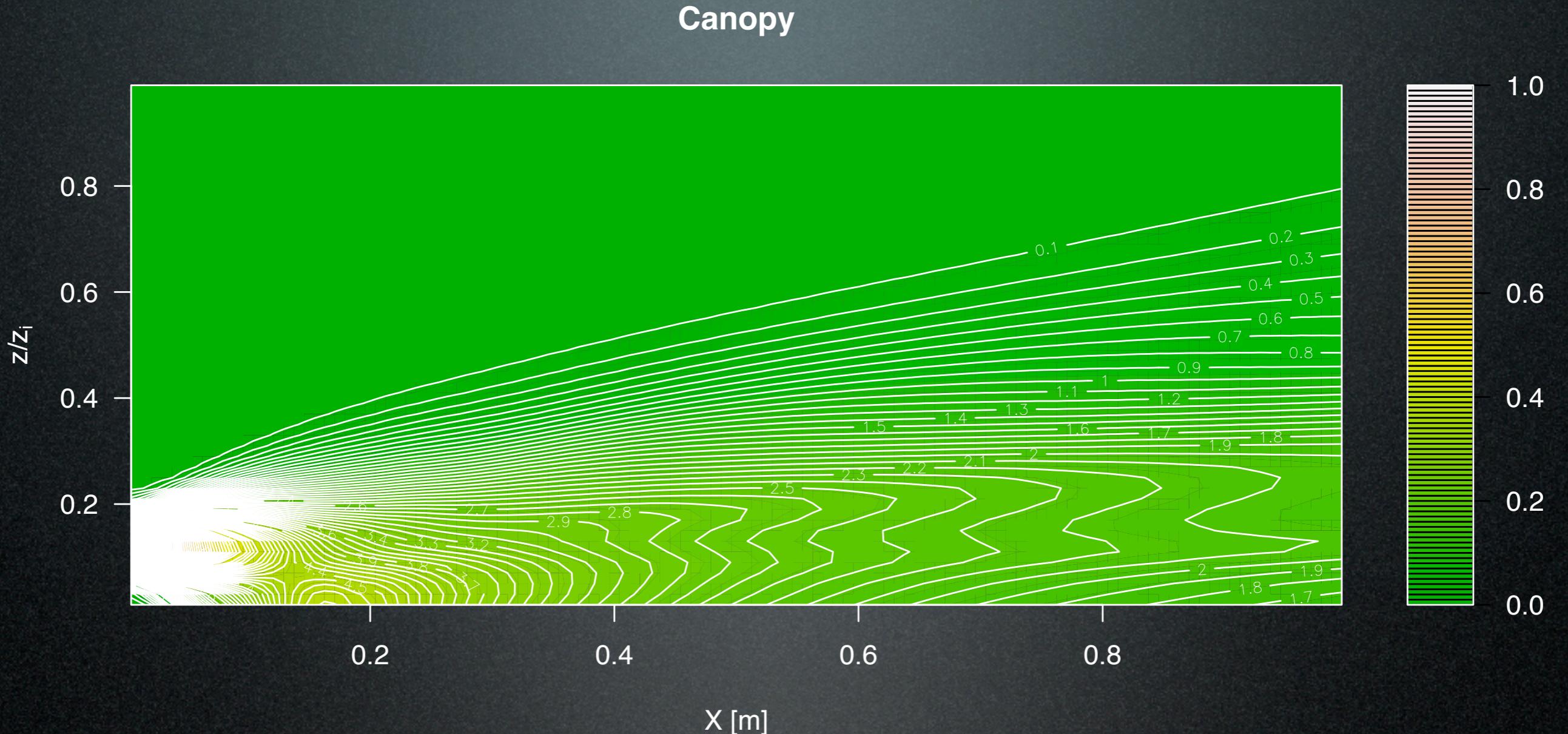


# Mean Concentration Field - CBL



$$\langle c(x, z) \rangle = \frac{Q}{U} \int_0^{z_i} p_{zr}(x, z, z_m) p_m(x, z_m) dz_m$$

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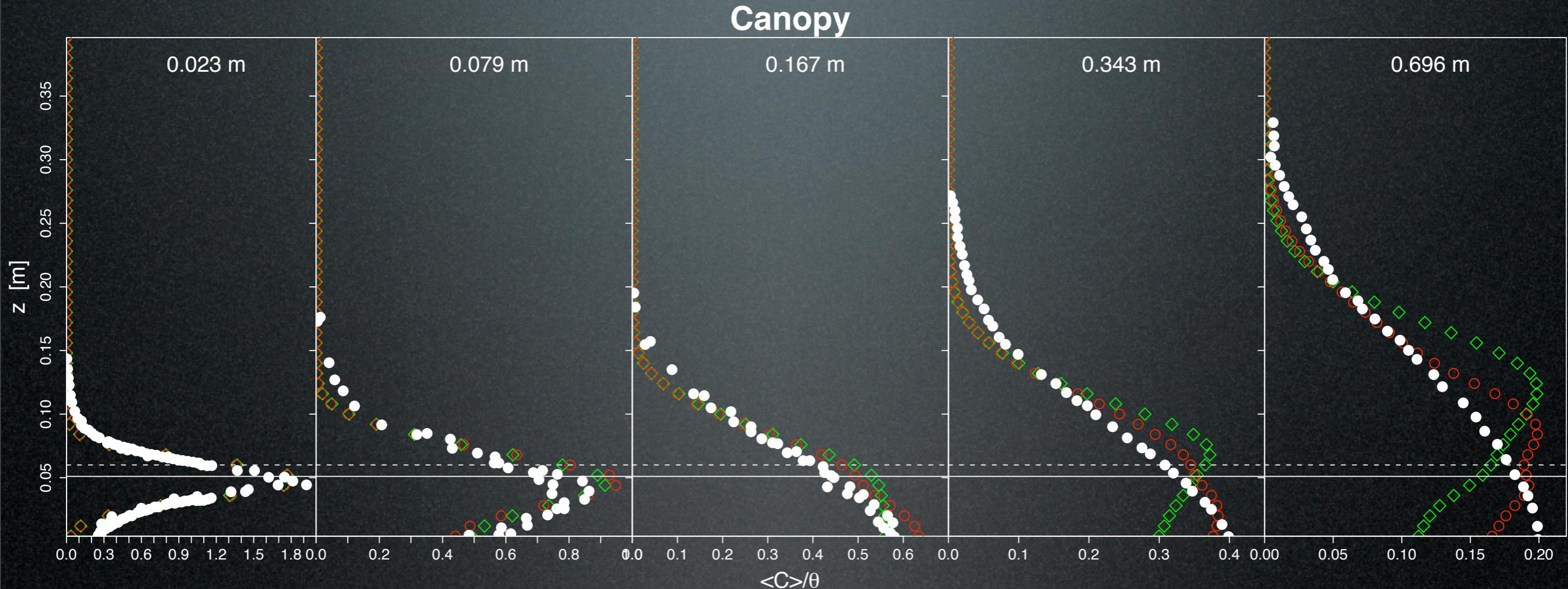


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# Ground Level Mean Concentration - CBL



# Mean Concentration Profiles- Canopy



Legg et al. (1986) data



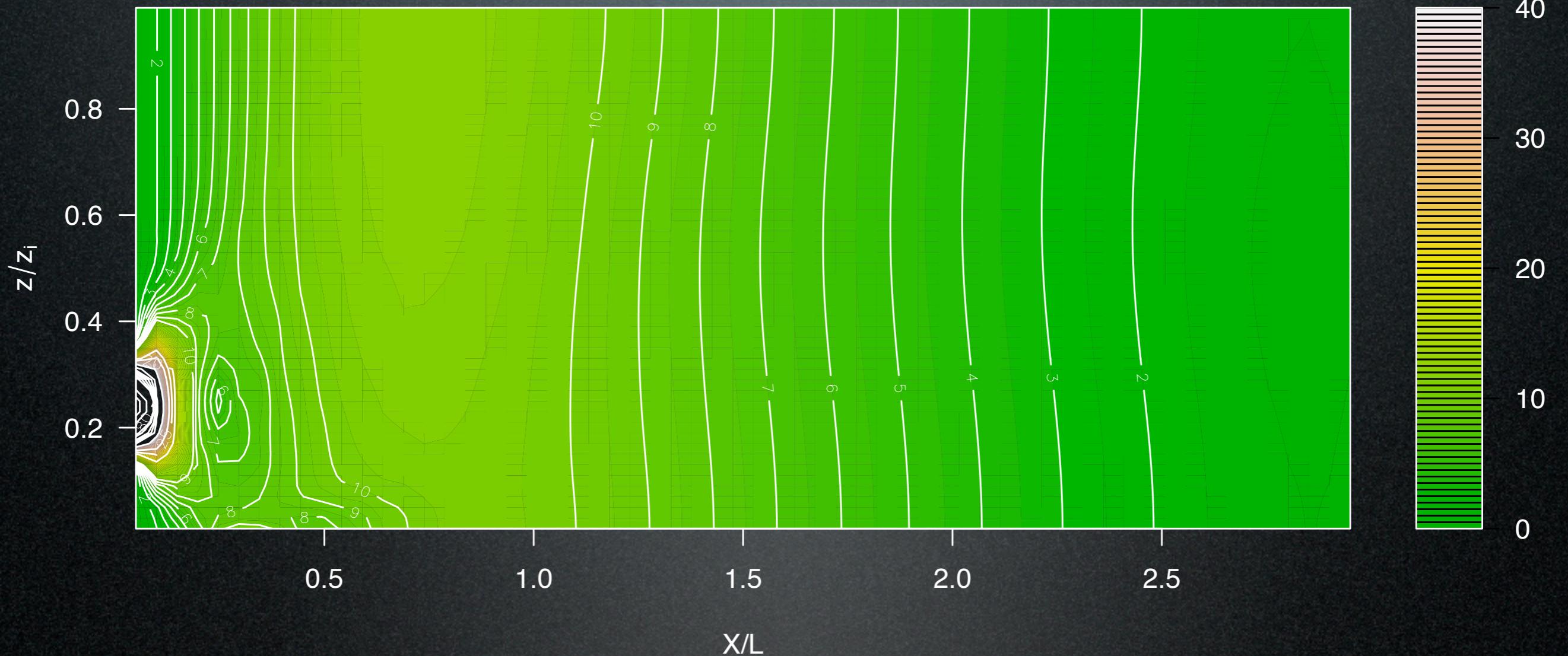
Fluctuating Plume Model, Gaussian Formulation



Fluctuating Plume Model, Skewed Formulation

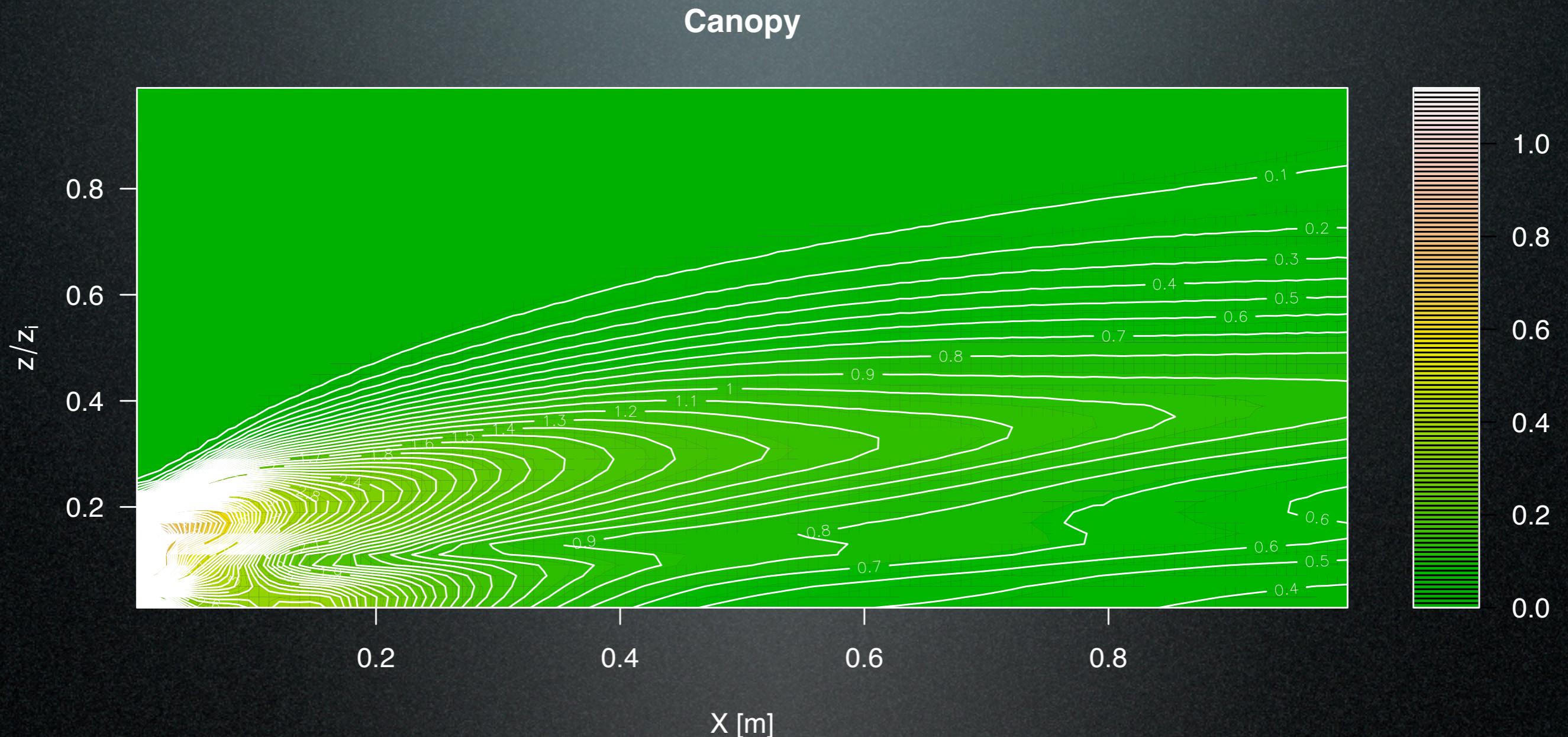
# Concentration Fluctuations' Field - CBL

CBL



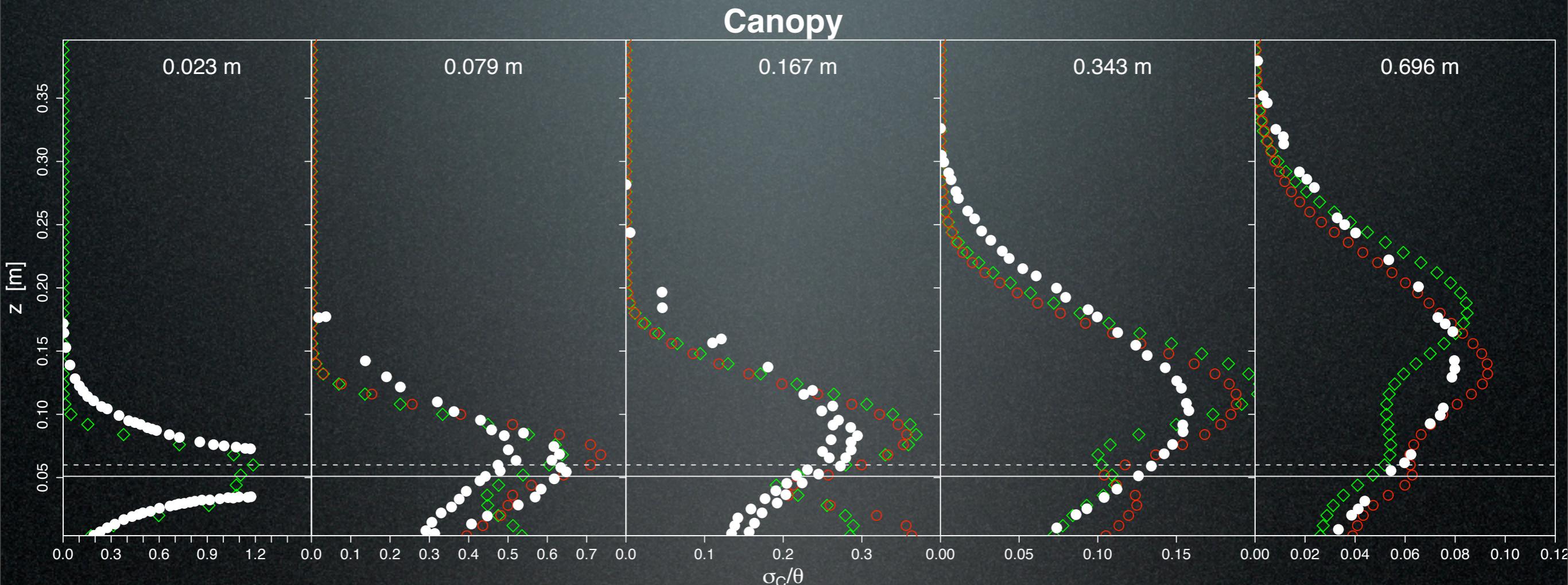
$$\langle c^2(x, z) \rangle = i_{cr}^4 \frac{\Gamma(1/i_{cr}^2 + 2)}{\Gamma(1/i_{cr}^2)} \left(\frac{Q}{U}\right)^2 \int_0^{z_i} p_{zr}^2(x, z, z_m) p_m(x, z_m) dz_m$$

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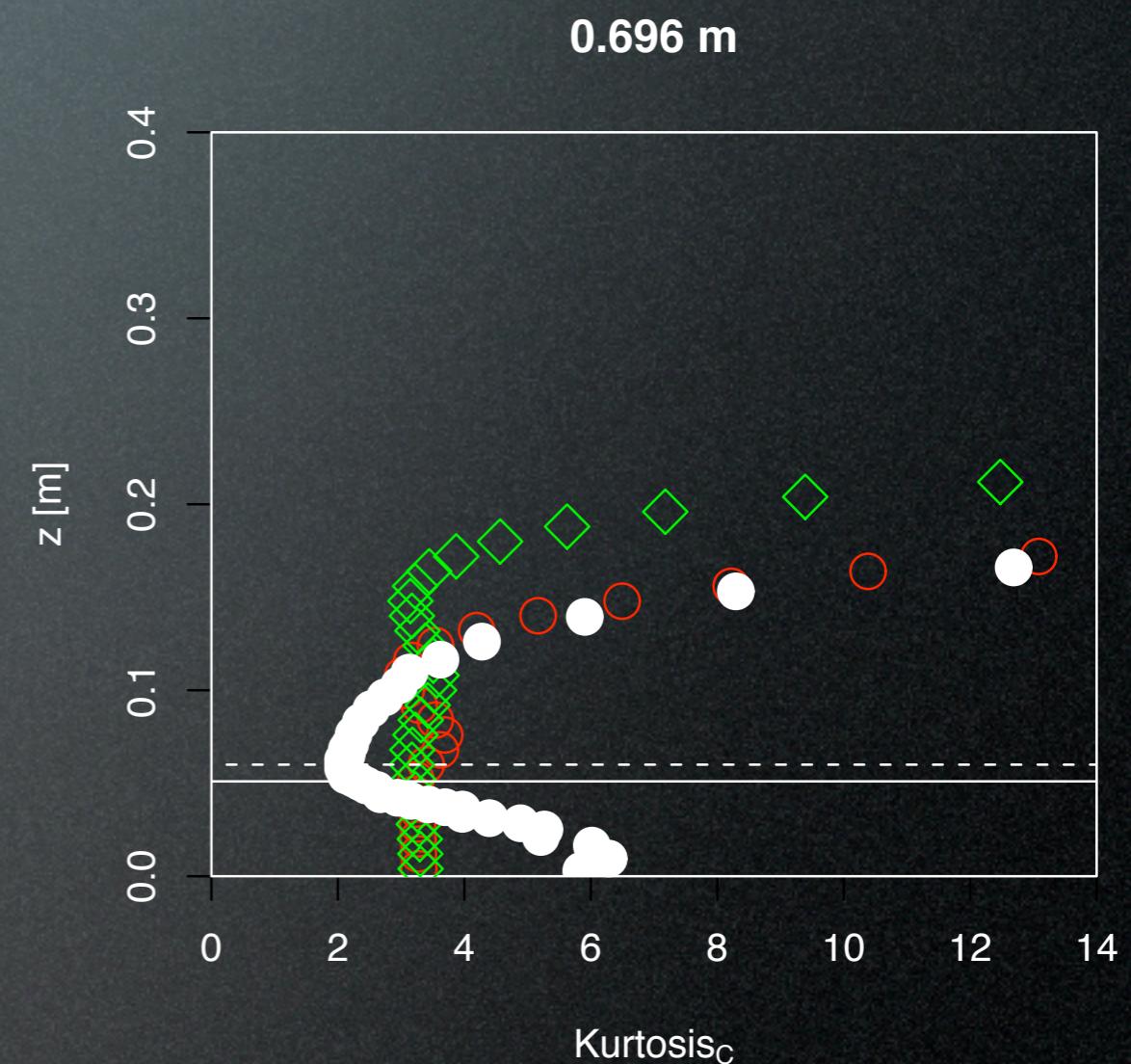
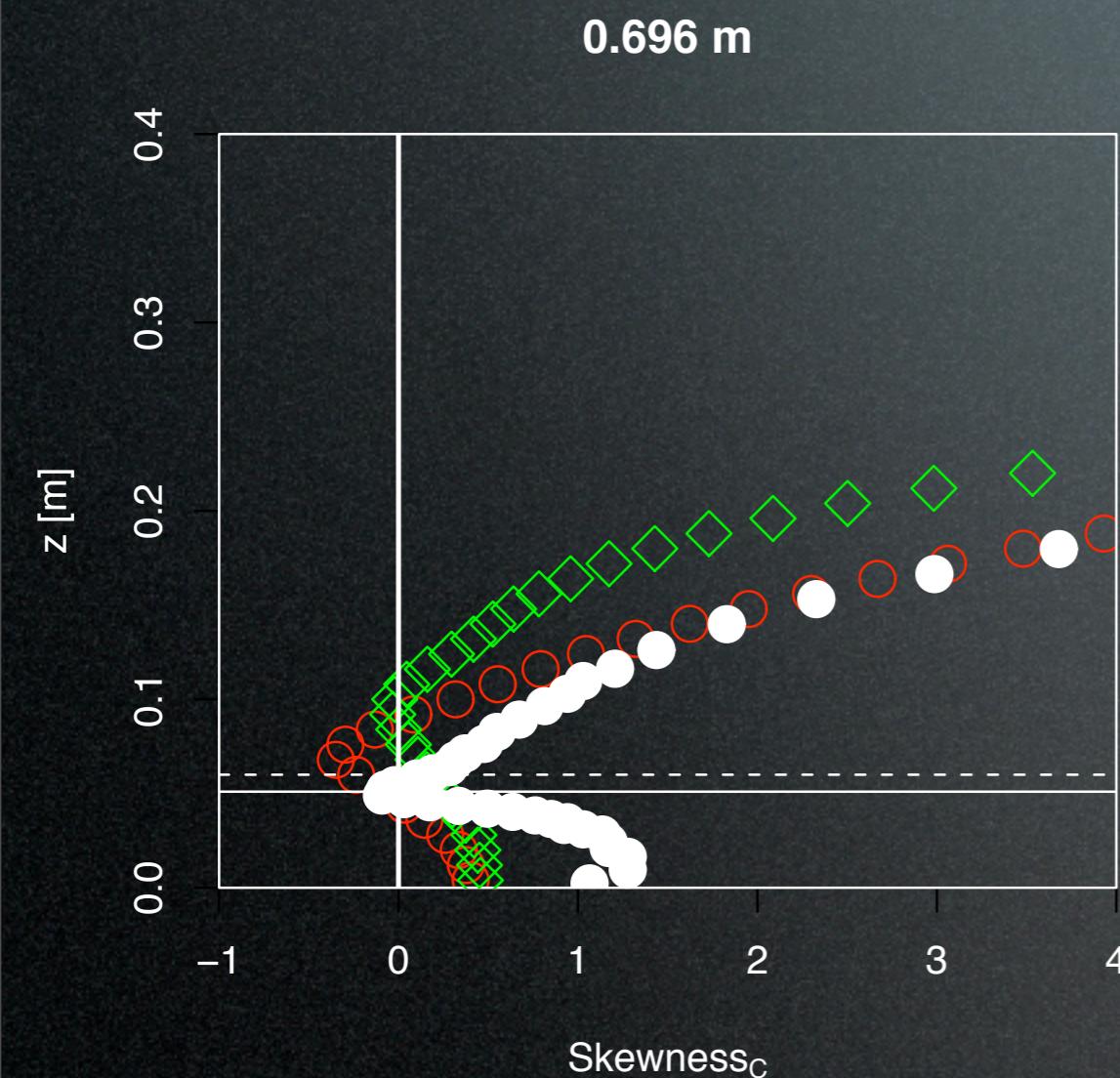
Fluctuating Plume Model, Gaussian Formulation



Fluctuating Plume Model, Skewed Formulation

# High Order Concentration Statistics- Canopy

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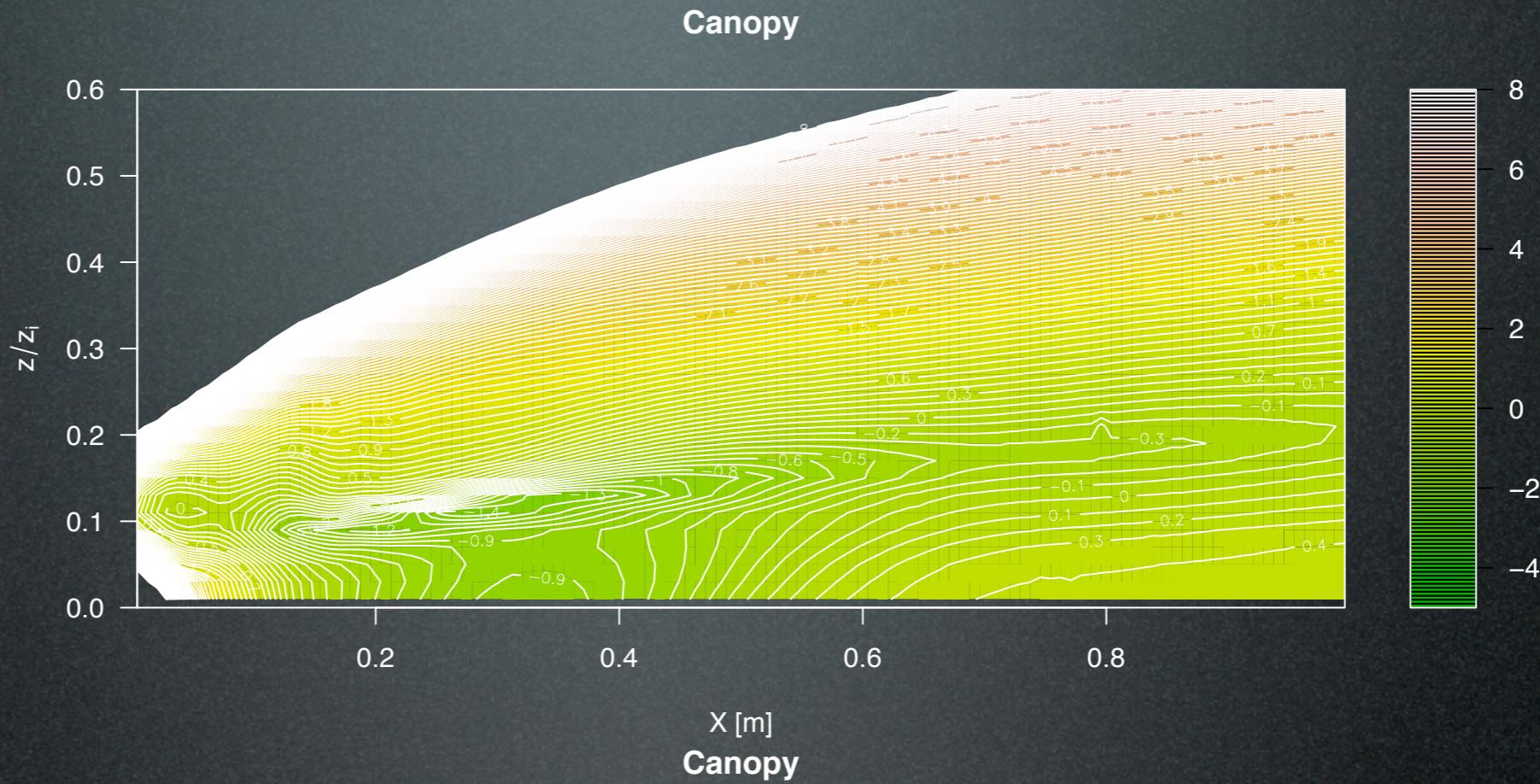
Coppin et al. (1986) data

Fluctuating Plume Model, Gaussian Formulation

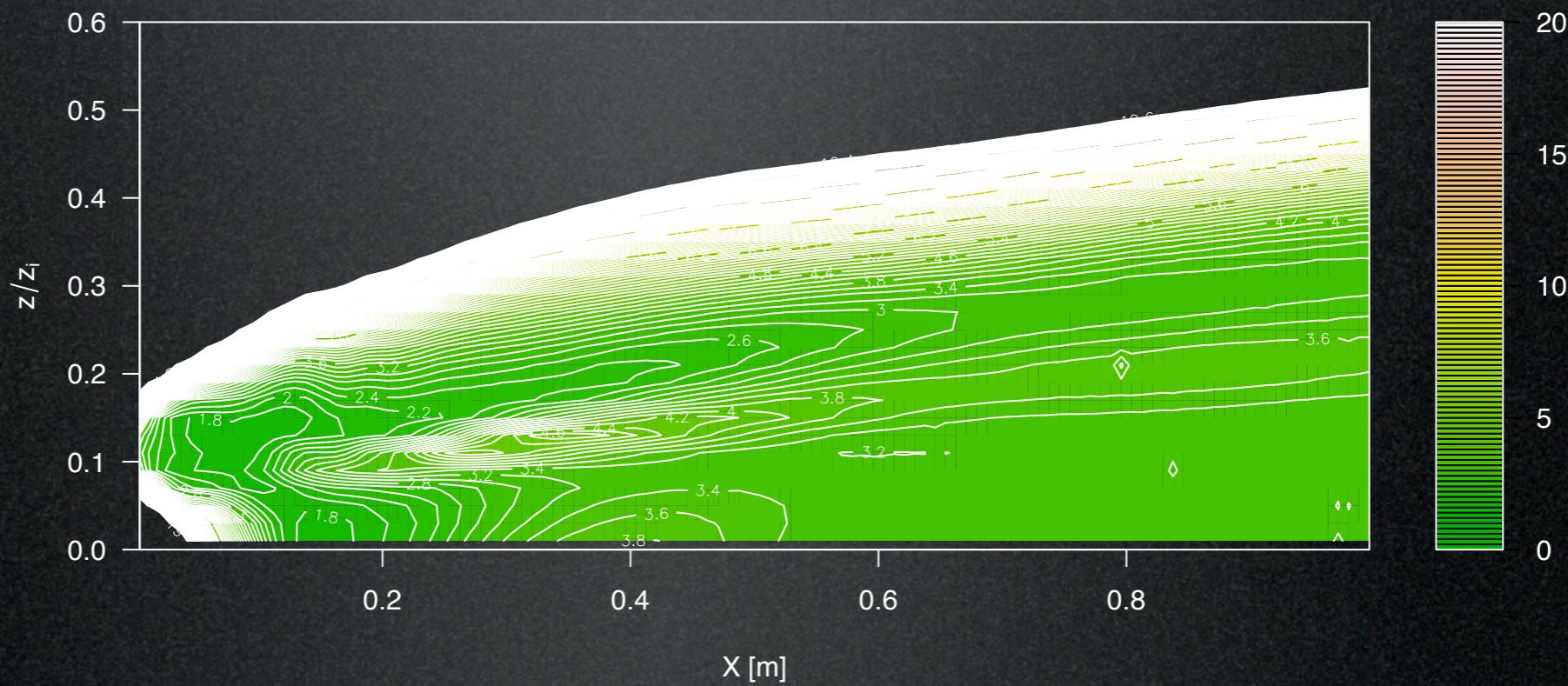
Fluctuating Plume Model, Skewed Formulation

# High Order Concentration Statistics- Canopy

Skewness



Kurtosis



# Conclusions

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Need of datasets.

Thank you!

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